

Abstract

A method for controlling vehicle dynamics in a motor vehicle,
at least one sensor recording at least one measured value; at
5 least one actuator for controlling vehicle dynamics being
driven as a function of the at least one measured value; at
least one image sensor system generating image information
from the motor-vehicle surround for controlling vehicle
dynamics; at least two image sensors being provided which
10 essentially record the same scene.

(Figure 3)